## Comprehensive evaluation of photovoltaic system using MATLAB/Simulink

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Absract-This paper presents modeling and simulation of PVA system in matlab simulink. The model based on exponential equation of pv module. It needs less input values and is more accurate. Here by varying temperature and irradiance as input variables we obtained the I-V, P-V characteristics and hence the harmonic distortion analysis can be made in different phases of supply system. The model has been validated with experimental data of a commercial PV module KC200GT.

### **Key Words**

Photo voltaic (PV), Matlab, Modelling, (RES)-Renewable energy source, MPPT.

Non linear I-V characteristics of P-V Cell(Nomenclature)

Ipv,cell-	current generated by incident
	light
Id	shocley diode equation
I0,cell	Reverse saturation current q
	electron charge
k	Boltzman constant
Т	temperature of p-n junction
a	diode ideality constant
Io	saturation current of array
Vt	thermal voltage or array
Ns	cell connected in series
Np	cell connected in parallel
Rs	equivalent series resistance
Rp	equivalent parallel resistance
Isc	short circuit current
Voc	open circuit voltage

(O,Isc)	short circuit point
Kv	voltage coefficient
Ki	current coefficient
P max,m	maximum power
Pmax,e	maximum experimental
	Power from data sheet
(Voc ,0)	open circuit point
(Vmp,Imp)	Maximum power point
Ipv,n	Light generated current at
-	nominal condition at ( 25 <sup>0</sup> c
	and 1000 $W/m^2$ )
<b>T</b>	actual Temperature
Tn	nominal temperature
G	Solar irradiance
Gn	nominal irradiance

**Introduction**-With the rapid development of study on solar cells, many models are presented to describe the characteristics of solar cells. This method helps us to construct the circuit model of pv cell. Computer simulation seems to reduce the tests for solar cells .This model accepts irradiance and temperature as environmental parameters as input variables, simulate the I-V characteristics of solar cells.



Fig-a, P-V Cell, P-V Module, P-V Array

combine to form PV module, no of module combine to form PV array.

### Maximum power point tracker system(MPPT)

MPPT controller is a power electronic DC/DC chopper or DC/AC inverter system inserted between the PV array and its electric load to achieve the optimum characteristic matching.The p-v array simulation model helps in study of MPPT. Is very important consideration that is taken into account when building new a photovoltaic power system. In order to extract maximum power output from a PV array under varying atmospheric conditions maximize the return to on initial investments. This technique is based on their speed of locating the maximum power point (MPP) of a PV array under given atmospheric conditions, besides the cost and complexity of implementing them.



Fig-b, P-V Cell model-Circuit Diagram

Shunt diode ideality factor is set to achieve the best curve match.

Series resistance  $(\mathbf{R}_s)$ : gives a more accurate shape between the maximum power point and the open circuit voltage.

Temperature dependence of the reverse saturation current of the diode is  $(I_d)$ .

Temperature dependence of the photogenerated current is  $(I_{pv})$ . Current source: proportional to the light falling on the cell in parallel with a diode.

The photovoltaic array can be simulated with an equivalent circuit model based on the photovoltaic model given below,



Fig-c, characteristics I-V curve of a practical PVA device and the three remarkable points: short circuit  $(0, I_{sc})$ , maximum power point  $(V_{mp}, I_{mp})$  and open circuit  $(V_{oc}, 0)$ .

The I-V characteristic of the ideal photovoltaic cell is

$$I = I_{pv,cell} - I_{0,cell} \left[ \exp\left(\frac{qV}{akT}\right) - 1 \right] \dots 1$$

The light generated current of the photovoltaic cell depends linearly on the solar irradiation and is also influenced by the temperature is given by

$$I_{pv} = I_{pv,n} + K_I \Delta_T \frac{G}{G_n}$$

....2

The diode saturation current  $I_o$  and its dependence on the temperature may be expressed by

$$I_0 = I_{0,n} \left(\frac{T_n}{T}\right)^3 \exp\left[\frac{qE_g}{aK} \left(\frac{1}{T_n} - \frac{1}{T}\right)\right] \qquad \dots 3$$

where Eg is the bandgap energy of the semiconductor (Eg  $\approx 1.12$  eV for the polycrystalline Si at 25 °C, and  $I_{o,n}$  is the nominal saturation current.  $V_t$  = NskT/q is

the thermal voltage of the array with Ns cells connected in series.  $I_o$ , n is the nominal saturation current, with Vt, n being the thermal voltage of Ns series-connected cells at the nominal temperature  $T_n$ .

$$I_{0,n} = \frac{I_{sc,n}}{\exp\left(\frac{V_{oc,n}}{aV_{t,n}}\right) - 1} \dots 4$$

Maximum experimental power from datasheet

$$P_{\text{max},e} = V_{\text{mp}} \left\{ I_{\text{PV}} - I_0 \left[ exp\left(\frac{q}{kT} \frac{V_{\text{mp}} + R_s I_{\text{mp}}}{aN_s}\right) - 1 \right] - \frac{V_{\text{mp}} + R_s I_{\text{mp}}}{R_p} \right\}$$

For any value of Rs there will be a value of Rp that makes the mathematical I-V curve cross the experimental (Vmp, Imp) point.

$$R_{p} = V_{mp} V_{mp} + I_{mp}R_{s} / \left\{ V_{mp}I_{pv} - V_{mp}I_{0} \exp\left[\frac{V_{mp} + I_{mp}R_{s}}{N_{s}a}\frac{q}{kT}\right] + V_{mp}I_{0} - P_{max,e} \right\}$$

#### Algorithm to adjust the I-V model



Fig.d-Flowchart

## P-V Array equivalent circuit block model using Matlab / Simulink



Fig .e-Matlab model of P-V system



Fig.f- Subsystem for calculation of  $I_m$ 



Fig.g- Subsystem for calculation of  $I_{pv}$ 



#### Fig.h- Subsystem for calculation of $I_o$

🙀 newmodelwithfilter/Solar Energy System/Subsystem3 \*

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Inputs:

Temperatur

[K]

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#### **Simulation Results**

The output of a model is evaluated with typical Parameters of the KC200GT solar array at  $25^{\circ}$ C, 1.5AM, 1000W/m<sup>2</sup>

TABLE I				
Imp	7.61A			
Vmp	26.3V			
Pmax,e	200.143W			
Isc	8.21A			
Voc	32.9V			
Kv	-0.123 v/k			
Ki	0.0032 A/k			
Ns	54			



Fig.i-subsystem of input as temperature and irradiance



Fig.j-Subsystem of Photovoltaic Array Model

Fig.k-Simulated Current and voltage curve of KC200GT at  $25^{\circ}$ c and 1000 W/m<sup>2</sup>



Fig.1-Simulated Power and voltage curve of KC200GT at  $25^{\circ}$ c and 1000 W/m<sup>2</sup>

# 1000 → [G] Npp √[Nop] Nss → [Nis]

Normal



Fig.n- Phase to phase inverter voltage after filter



Fig.o-Phase to phase Inverter voltage without filtering



Fig.p- Phase to ground transformer voltage



Fig.r- grid current and grid voltage



Fig.q- load current and load voltage



Fig.s- V-I waveform of ac bus



Fig.t- Active and Reactive power at load



Fig.u- Active and Reactive power at grid



Fig.v- THD of simulated output at (60 hz)







Fig.x- THD of simulatd output(40 hz)



Fig.y-Total harmonic distortion with filter



Fig.z-Total harmonic distortion without filter

### **Result Analysis**

The maximum output power form the array under the stated conditions (1000 W/m2 and 25 C) should have been 200W.

#### Harmonic analysis of voltage waveform

#### Table-II

1. At 60 Hz	THD is-	.23%
2. At 50 Hz	THD is-	39.0%
3. At 40 Hz	THD is-	108.15%

Table-III

1.THD filter	with	39.02%
2.THD filter	without	45.13%

It can be seen a voltage waveform distortion caused by electronic devices — inverters used for energy conversion in DC/AC module, shows harmonic distortion in phase voltage. As we know due to non linear load a lot of harmonic distortion occurs in supply system, due to non linear load harmonic component occurred in voltage waveform of different phases .

# The simulation model allows studies such as:

- renewable energy sources electrical parameters (powers, voltages, currents etc.)
- renewable energy sources constructive parameters (blades length and number of wind turbine, PV panels' number)
- voltage and frequency control (control algorithms)
- electrical energy conversion (type of DC/AC conversion)
- Consumer modeling and control.
- Power quality distortion phenomena and analysis.
- Renewable energy availability.

#### Conclusions

The full mathematical models for PV array modules were fully developed including the inherently nonlinear I-V characteristics and variations under ambient temperature and solar irradiation conditions.Grid connected renewable photovoltaic dynamic control strategies were digitally simulated and validated, using matlab/simulink/simpower system software environment. The dynamic controllers require only the measured values of voltage and current signals in addition to the motor speed low cost sensors and transducers.

The proposed Grid connected renewable photovoltaic schemes are suitable for resort/village electricity application in the range of (1500 watts to 50000 watts), mostly for water pumping, ventilation, lighting, irrigation and village electricity use in arid remote communities.

#### Future scope

It is necessary to validate the proposed novel dynamic maximum photovoltaic power tracking control strategies by a specific laboratory facility using the low cost micro controllers.

The proposed dynamic effective and robust error driven control strategies can be extended to other control system applications. They are also flexible by adding supplementary control loops to adapt any control objectives of any systems. Further work can be focused on Artificial Intelligence (AI) control strategies.

The research can be expanded to the design and validation of dynamic FACTS with stabilization and compensation control strategies for other stand-alone renewable energy resource schemes as well as gridconnected renewable energy systems to make maximum utilization of the available energy resources.

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