#### Convergence of Recurrent Neural Networks Using Partially Trained ANN

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#### Abstract

Artificial Neural Networks are known for non linear mappings of complex systems. However these are static mapping tools in the sense that the knowledge update is based on static data provided for training the network. Simple recurrent neural networks (SRN) such as the one proposed by Elman have the capacity of dynamic learning, but are found to possess severely hampered learning capabilities due to convergence problems. A novel way of overcoming the problem of convergence is proposed through this paper by using a Hybrid Recurrent Neural Network modelled from an Artificial Neural Network (ANN) possessing similar architecture.

**Keywords:** Elman networks (ENs), extended Elman networks, backpropagation, RNN convergence, hybrid RNN (HRNN).

#### **1. Introduction:**

Artificial Neural Networks (ANN) is a field of machine learning which in a way represents, to a large extent, the human style of learning. The study of ANN is inspired by the working principles of the human brain and by the way in which a human brain is able to process a large data by way of parallel processing and is able to retrieve the data at will [1]. Fundamentally, an ANN network does not need any knowledge of the process that it is trying to model, as it learns on the basis of the examples or the experimental data being supplied to it during training U. J. Amonkar Goa College of Engineering, Goa, India

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[2, 3]. It is exactly because of this advantage that a tool such as ANN is preferred over other prediction tools, such as statistical or numerical methods [3].

Artificial Neural Networks are thus mathematical models representing the gathering and processing data in a way similar to the human brain [4-7]. The neural network's ability to carry out the computations relating the inputs and outputs is inspired by the massive parallel and distributed processing of biological neurons. Neural Networks (NN) are able to perform complex mappings of input and output elements. When properly trained, ANN nicely generalizes the input output relationship by understanding the underlying relationship functions between input and output parameters, even from a limited data set. There are a variety of ANN architectures available, but the literature [8, 9] suggests that the ones which are being widely used are the supervised learning Feed Forward Neural Networks (FFNN). In FFNN the output of each neuron in a layer is passed on to each neuron in the subsequent layer, through connections called as synaptic weights. The knowledge of mapping is stored in the network in the form of these weights. The network is fed with the input vectors and the target output vectors one by one. The network calculates the output from the input data and in case of supervised learning this is compared with the target output. The error in the output is used to update the weights.

There are a lot of learning algorithms proposed in the studies on Neural Networks, but the one which is used most widely is the back propagation algorithm [1, 4, 8, 9, 10]. When the error is propagated backwards in the network, after each set of inputs is presented to the network, this algorithm uses the gradient descent approach in minimizing the Mean Squared Error (MSE) on the MSE weight planes and adjusts the connection weights accordingly, thus making the network learn. The entire set of inputs is presented (epoch) to the network again and again till the MSE reduces to some predetermined value. The training time and the number of epochs required to train the network depend upon, the number of hidden layers in the MLP, the number of neurons in each layer, learning rate parameter and momentum factor. There is no authentic information as to determine the number of hidden layers required for formulating a FFNN. One hidden layer is good enough to map most of the input output relationships, but more complex mappings are better achieved with two hidden layers [11]. Similarly there is no formula or relationship to fix the number of neurons in each hidden layer and this is done by trial and error [4, 11].

In general a FFNN would look like the network shown in Fig: 1. The inputs from i<sup>th</sup> layer ( $x_i$ ) are fed to the neurons in the first hidden (j<sup>th</sup>) layer. Each neuron in this layer receives the inputs from each neuron in the input layer through a weighted connection ( $w_{ji}$ ). In the neuron the weighted sum of inputs  $\Sigma w_{ji}x_i$  is calculated. The activation function to be used has to be continuous so that back propagation algorithm can be used. The reason of using a activation function is to limit the output of the neurons within a pre set range. The activation function most often used is the sigmoid function which is continuous, monotonic non decreasing and nonlinear which is as follow

$$y = \frac{1}{1 + e^{-x}} \tag{1}$$

In the recent past quite a few Recurrent Neural Network (RNN) architectures have been studied [12-16]. Recurrent networks are neural networks with one or more feedback loops, in which the loops may be local or global. RNN can be divided into two broad categories depending on whether the states of the network are guaranteed and observable or not. Observable state is one in which the state of the network can be derived by observing only the inputs and outputs [12]. A model which falls into this class was proposed by Narendra and Parthasarathy [17] and had time delayed outputs as well as inputs fed to a Multi Layer Perceptron (MLP) which computed the output using the recent state dynamics. However, network having hidden dynamic states are not observable [12]. Single layered and multi layered recurrent networks are being extensively studied in recent times. A typical single layered RNN was the one proposed by Elman in 1990 [14]. In this network, the hidden layer is copied in a virtual or context layer and the feedback is given back to the same layer along with the next set of inputs in the next time step as seen in Fig: 2. The Elman network can be extended for a multilayered network with the temporal context layer providing feedback at each subsequent time step. Such a network is shown in Fig: 3. The convergence of a Simple Elman Recurrent Neural Network (SRN) has been established. The computational power of Elman networks is as good as that of finite state machines (FSM) [18]. In addition any network having additional layers between input and output layer than Elman network, possesses the same FSM power. The convergence of RNN has been active subject of research in machine learning. An extended back propagation algorithm for Elman networks reported a better convergence, faster training and better generalization [19]. In this algorithm, use is made of adaptive learning scheme coupled with adaptive dead zone to improve convergence speed.

In this paper we try to develop a novel way of improving the convergence of Elman (SRN) using the borrowed weights of a partially trained FFNN into an Elman network with single hidden layer or an extended Elman network having more than one hidden and context layer. The paper further highlights the fact that the recurrent neural network so formulated performs the task of predictions of outputs from a given set of inputs comparable to that performed by the fully trained FFNN, from which the weights were borrowed to formulate the RNN, together with better convergence.



Fig1. Schematic diagram of FFNN



Input Layer

#### Fig2. A simple RNN



#### Fig3. An extended simple RNN

#### 2. Data Generation:

The data for the ANN and proposed RNN has been taken from the work of M. A. Herbert [20]. The work dealt with study of microstructural details and mechanical properties of Al-4.5Cu-5TiB<sub>2</sub> composite when rolled from mushy state in as cast and in pre hot rolled condition. The data is presented in Table: 1.

Two ANNs have been trained. The first ANN predicts small and large grain sizes ( $\mu$ m) from four inputs namely, Material type (as cast or pre hot rolled), % thickness reduction during rolling, % liquid volume fraction which determines the mushy state condition during rolling initiation and % TiB<sub>2</sub> (wt %) in the composite. ANNs were formulated using different values of learning rate parameter ( $\eta$ ) and momentum factor ( $\alpha$ ). The FFNNs with architectures 4-7-4-2 and 4-9-9-2 with  $\eta$  = 0.85 and  $\alpha$  = 0.65 were found to converge to a MSE of 0.000362612 after 15 lakh epochs and 0.00017 after 277356 epochs respectively.

The second ANN predicts hardness of the composite (H<sub>v</sub>) as output from five parameters provided as inputs. The input parameters were Material type, % thickness reduction, % liquid volume fraction, large grain size and small grain size. The ANN with 5-5-3-1 architecture and 5-9-6-1 architectures were trained with  $\eta = 0.85$  and  $\alpha = 0.65$  and converged nicely to a MSE of  $9.75*10^{-5}$  after 325000 epochs and a MSE of  $9.8774*10^{-5-}$  after 345000 epochs.

#### 3. RNN Modeling:

Elman Simple Recurrent Network (SRN) was modeled for Grain sizes as well as hardness predictions. The SRN with two context layers were tried with two hidden layer and with different combinations of number of neurons in each layer for different combinations of  $\eta$  and  $\alpha$ . The networks failed to converge for a variety of combinations mentioned above. The SRN with Elman architecture uses a context layer that contains the same number of neurons as that in the hidden layer. The output of each hidden neuron which is being copied in the context layer will contain neurons with exciting as well as inhibiting signals. These neurons then pass on the signals through weighted connections to each neuron in the current hidden layer in the next time step along with the signals these neurons in the current hidden layer receive from the neurons in the previous layer. Due to this, the previously excited neuron or the neuron which otherwise would have received a consistent excited signal from previous layer neurons may get inhibiting signals from the context layer neurons or vice versa. This probably, does not allow the network to progressively move along the path of negative gradient on the MSE weight plane. Such a phenomenon is likely to cause a oscillatory profile on the MSE synaptic

Table1. Experimental data of AI-4.5Cu Alloy and AI-4.5Cu-5TiB <sub>2</sub> composite rolled from mushy state
in as cast and pre hot rolled condition [21].

Specimen Descriptions	Liquid Volume Fraction	As cast Al-4.5Cu- 5TiB <sub>2</sub> Composite samples subjected to mushy state rolling		Pre hot rolled Composite samples subjected to mushy state rolling		Grain sizes of Al-4.5Cu alloy samples subjected to mushy state rolling	
		Grain s	ize ( µm )	Grain size ( µm)		Grain size ( µm)	
		Large	Small	Large	Small	Large	Small
As cast		50	± 8	52 ± 15	28 ± 9	44	± 6
2.5%	f <sub>1</sub> ~ 0.1	62 ± 14	27 ± 12	43 ± 16	27 ± 13		
thickness	f <sub>1</sub> ~ 0.2	58 ± 18	33 ± 11	42 ± 18	26 ± 11		
reduction	f <sub>1</sub> ~ 0.3	66 ± 15	37 ± 10	47 ± 20	25 ± 11	329 ± 204	158 ± 91
5%	f <sub>1</sub> ~ 0.1	54 ± 16	25 ± 9	42 ± 16	26 ± 11		
thickness	f <sub>1</sub> ~ 0.2	51 ± 11	31 ± 10	41 ± 15	25 ± 12		
reduction	f <sub>1</sub> ~ 0.3	55 ± 14	32 ± 10	46 ± 17	24 ± 11	363 ± 225	157 ± 86
7.5%	f <sub>1</sub> ~ 0.1	62 ± 20	32 ± 13	40 ± 15	26 ± 10		
thickness	f <sub>1</sub> ~ 0.2	48 ± 19	26 ± 12	39 ± 15	25 ± 11		
reduction	f <sub>1</sub> ~ 0.3	53 ± 18	27 ± 13	45 ± 17	24 ± 09	383 ± 222	158 ± 98
10% thickness	f <sub>1</sub> ~ 0.1	49 ± 17	29 ± 11	47 ± 18	32 ± 13	351 ± 218	194 ± 96
reduction	f <sub>1</sub> ~ 0.2	47 ± 14	30 ± 12	43 ± 16	25 ± 11	325 ± 217	176 ± 103
	f <sub>1</sub> ~ 0.3	54 ± 12	26 ± 11	45 ± 16	27 ± 12	357±217	155 ± 87

weight plane, which is exactly witnessed while training the simple Elman recurrent network.

In order to overcome this shortcoming, various strategies discussed hereunder were tried;

a. The networks with single hidden layer were trained for the same architectures mentioned earlier with different combinations of  $\eta$  and  $\alpha$ . During training, it was observed that the

network does not converge. Initially during training it learns nicely. But as the training progresses, the network starts oscillating randomly. Further it is observed that the oscillations decrease and the network stops learning and MSE reaches a value much higher than the pre set value which in our case is selected as 0.0001, thus indicating that the network has not been able to map the input output pattern.

- The network model was slightly changed b. now, with the neurons in the hidden layer giving feedback only to itself. The networks were modeled for each of the case with similar architectures discussed at (a) above with different combinations of  $\eta$  and  $\alpha$ . It was observed that the networks still oscillate during training and fail to converge to the pre-set value, but a better convergence is seen as indicated by slightly lower MSE indicating that learning capability of the network has slightly improved. But the convergence obtained is nowhere near the pre-set value of MSE. Hence, this strategy, though could not be discarded totally, was found to be ineffective.
- In the modified model stated at (b) above, c. the weight vectors of a partially trained ANN with similar architecture were borrowed. The ANN network is partially trained till a steep negative gradient is identified on the MSE weights plane indicating the downward movement of MSE. The SNN is then modeled with similar architecture as that of partially trained ANN. The weight vectors of the SNN from input layer to hidden layer 1, hidden layer1 to hidden layer 2 and from hidden layer 2 to output layer are replaced by the corresponding weight vectors of partially trained ANN. The biases for different layers except the context layers of the SNN are also replaced by the corresponding biases from the partially trained ANN. The weight vectors from the context layer neurons to hidden layer neurons (each neuron to itself) is taken as a zero vector (unbiased) and so also the biases to these neurons in context

layer are kept as zero. Once the architecture is finalized this way, the network is trained. Upon training with the same values of  $\eta$  and  $\alpha$  as that used for partially trained ANN, the SNN so formulated is found to converge excellently. The convergences of SNNs so modeled are found to perform better as compared to the parent ANNs from which these have been modeled. The performance of the SNNs modeled from the parent ANNs is demonstrated using the following cases. We have named this SNN as Hybrid RNN (HRNN).

**3.1.** Modeling of Hybrid RNN for Grain size prediction:

#### 3.1.1 HRNN with 4-7-4-2 architecture:

The Elman RNN network selected has 4 input neurons, 7 neurons in hidden layer 1, 4 in hidden layer2 and 2 output neurons. The network was trained with learning rate parameter as 0.85 and momentum factor 0.65. Initially the network is trained as an ANN network. Table: 2 gives the details of the error in prediction in terms of MSE existing at various stages of network training. The ANN network converges to a MSE of 0.000362612 after 15 lakh epochs. To obtain the HRNN the ANN is now trained till 50000 epochs. The weights of this ANN are then borrowed in the input weights file for RNN training. The network is found to oscillate after it reaches a MSE of 0.00205. This happens, probably due to the fact that the ANN training up to 50000 epochs has not provided sufficient gradient descent on the MSE weights plane for the Hybrid RNN to further travel in the direction of negative gradient.

Further to this, the ANN was trained up to 100000 epochs and the weights were borrowed in the input weights file for RNN training. The results were better than the first case, but the convergence was found to be slow. After training for150000 epochs, the MSE is found to be 0.0013. Hence in the next step the ANN is trained for 500000 epochs and subsequently, the weights are borrowed in the input file for RNN training. It was found that after training for around 227000 epochs, the network converged satisfactorily.

#### 3.1.2 HRNN with 4-9-9-2 architecture:

Here the network is selected with 4 input neurons, 9 neurons each in second and third layer and 2 output neurons. Here the number of input patterns is taken as 240, just to emphasize that the number of input vectors has no great bearing on the convergence of Hybrid RNN. The ANN network is first trained until 50000 epochs and then hybrid RNN is constructed by borrowing weights of trained ANN. The network is further trained for 85000 epochs as it gave the same MSE as that of parent ANN when trained to 277356 epochs.

## Table 2: Variation of MSE with number of epochs

Sr.	Number of	MSE					
1	1 0.329771						
2	100000	0.00467185					
3	200000	0.002215					
4	300000	0.00153321					
5	400000	0.0014147					
6	500000	0.00129209					
7	600000	0.00105979					
8	700000	0.000684544					
9	800000	0.00056784					
10	1500000	0.000362612					
312	Modeling of	Hybrid <b>RNN</b> for					

### 3.1.2 Modeling of Hybrid RNN for Hardness prediction:

In a manner similar to the Hybrid RNN formulated for Grain size prediction, Hybrid RNN is constructed for Hardness as will be discussed in forthcoming sections.

#### 3.2.1 HRNN with 5-5-3-1 architecture:

Initially, the ANN for hardness prediction was trained with architecture of 5 input neurons, 5 and 3 neurons in hidden layer1 and 2 respectively and one output neuron. The network is trained to achieve a MSE of  $09.75*10^{-5}$  after 325000 epochs. The Hybrid RNN was constructed after training the above ANN for 50000 epochs in the same fashion as discussed earlier for grain size prediction. After around 200000 epochs, the hybrid RNN gave the same MSE as parent ANN.

#### 3.2.2 HRNN with 5-9-6-1 architecture:

Hybrid RNN is constructed from ANN having architecture as input layer 1: 5 neurons, Layer 2: 9 neurons, Layer 3: 6 neurons, Output: 1 neuron. The

Hybrid RNN was formulated after just 5000 epochs, when a steep downward trend was observed in MSE at a rapid pace. The Hybrid RNN gave a MSE of 9.8774\*10<sup>-5-</sup> after 124000 epochs while to obtain the same value of MSE 345000 epochs were required for training the ANN.

#### 4. **Results and Discussions:**

#### 4.1. Grain Size Predictions:

#### 4.1.1 HRNN with 4-7-4-2 architecture:

The results of the predictions and the comparison between the ANN network after 15 lakh epochs and HRNN after 2.24 lakh epochs is present in Table: 3 below.

It is seen that the maximum error is |0.58| % at 5% thickness reduction with 10% liquid volume fraction in the as cast composite for small grain size, while for large grain size it is also at the same location. However in the majority of the cases, the error with hybrid RNN is within |0.5|%. The HRNN is modelled after borrowing the weights from partially trained ANN after 5 lakh epochs. Further, the HRNN converged nicely to a MSE of 0.000362612. Thus to achieve the same degree of convergence HRNN has consumed 776000 lesser epochs as compared to that of parent ANN, thus giving a saving of more than 50% of computational time. Furthermore, the error in predictions too is quite insignificant in comparison with the parent ANN predictions for the same data.

#### 4.1.2 HRNN with 4-9-9-2 architecture:

The comparison of predictions between the parent ANN and Hybrid RNN is given in Table: 4 below for a MSE of 0.0001762 achieved by parent ANN after being trained using 277356 epochs. The HRNN was trained with 240 patterns to emphasize that the data set available for training has no much bearing on the implementation of the model. The total number of epochs of HRNN coupled with partially trained ANN works out to 135000 epochs, thus giving a saving in computation time in excess of 50%. It can be seen that the error in estimation with hybrid RNN with respect to Parent ANN is within 6%, while in majority of the cases the error is within 1%.

#### 4.2 HRNN for Hardness predictions:

In a manner similar to the Hybrid RNN formulated for Grain size prediction, Hybrid RNN is constructed for Hardness predictions.

#### 4.2.1 HRNN with 5-5-3-1 architecture:

Initially, the ANN for hardness prediction was trained with architecture of 5 input neurons, 5 and 3 neurons in hidden layer1 and 2 respectively and one output neuron. The network was trained to achieve a MSE of 09.75\*10<sup>-5</sup> after 325000 epochs. . The Hybrid RNN was then constructed after training the above parent ANN for 50000 epochs in the same fashion as discussed earlier for grain size prediction. After around 200000 epochs, the hybrid RNN gave the same MSE. The comparison of the predictions done by the parent ANN and the HRNN for hardness prediction with 5-5-3-1 architecture is presented in Table: 5. It can be seen that the error in estimation lies between |2.5%|, while the computational time is saved by 23%. It can also be seen that in majority of the cases, the error is within 1%. Fig: 4 shows the graph of comparison of variation of hardness predicted by ANN and Hybrid RNN for as cast Al-4.5Cu-5TiB<sub>2</sub> composite when rolled from mushy state with various liquid volume fractions at the initiation of rolling with 5-5-3-1 architecture. It can be seen from the graph that the plots for predictions with ANN and that with Hybrid RNN follow each other very closely. Maximum deviation is observed in case of predictions at 30% liquid volume fraction in the vicinity of 5% thickness reduction. Fig: 5 shows the plot of comparison of variation of hardness as predicted by ANN and Hybrid RNN with 5-5-3-1 architecture when Al-4.5Cu-5TiB<sub>2</sub> composite in pre hot rolled condition is rolled from mushy state at various thickness reductions. The rolling is initiated at mushy state corresponding to 10%, 20% and 30% liquid volume fractions respectively. It can be seen from Fig: 5 that the plots for predictions with ANN and hybrid RNN are almost identical indicating that the learning has been adequate and that both the networks have generalized quite nicely.

#### 4.2.2 HRNN with 5-9-6-1 architecture:

Hybrid RNN is constructed from ANN having architecture as 5 neurons in input layer, 9 neurons in

Layer 2, 6 neurons in Layer 3, 1 neuron in Output layer for hardness . The network was formulated after just 5000 epochs, when the down trend was observed in MSE at a rapid pace. The Hybrid RNN gave a MSE of  $9.8774*10^{-5}$  after 124000 epochs while to obtain the same MSE, 345000 epochs of ANN were required. Table: 6 gives the relative performance in prediction of hardness with HRNN with the parent



Fig4: Plot showing comparison of ANN and Hybrid RNN for hardness prediction when as cast Al-4.5Cu-5TiB<sub>2</sub> composite is rolled from mushy state with various thickness reductions



Fig5: Plot showing comparison of ANN and Hybrid RNN for hardness prediction when pre hot rolled AI -4.5Cu-5TiB<sub>2</sub> composite is rolled from mushy state with various thickness reductions

# Table3. Comparison of grain sizes by ANN Hybrid RNN after 2.24 lakh epochs of HRNN and 15 lakh epochs of ANN

	Input			output					
					Grain Sizes				
				lar	ge	04	Sm	nall	04
	Mat /					<sup>70</sup> Difference			<sup>%</sup> Difference
Sr. No.	Process	% TR $^{*}$	%LVF**	ANN	RNN	over ANN	ANN	RNN	over ANN
1	1	2.5	10	61.218	61.101	0.190139	28.124	28.037	0.307209
2	1	2.5	20	58.339	58.323	0.026569	33.370	33.364	0.018879
3	1	2.5	30	66.012	65.976	0.054232	36.223	36.2	0.064047
4	1	5	10	54.532	54.235	0.54335	23.870	23.732	0.578546
5	1	5	20	50.537	50.525	0.023745	28.842	28.841	0.004854
6	1	5	30	55.643	56.666	-1.83923	29.867	29.86	0.024776
7	1	7.5	10	61.727	61.623	0.168968	31.654	31.586	0.21482
8	1	7.5	20	47.586	47.582	0.007986	26.494	26.497	-0.01057
9	1	7.5	30	53.171	53.139	0.060559	27.758	27.751	0.022696
10	1	10	10	48.363	48.361	0.004135	31.307	31.306	0.002236
11	1	10	20	48.280	48.275	0.010149	28.316	28.318	-0.00671
12	1	10	30	52.639	52.609	0.057751	27.881	27.875	0.020085
13	2	2.5	10	43.255	43.218	0.085769	27.893	27.880	0.047323
14	2	2.5	20	43.189	43.194	-0.01343	27.267	27.271	-0.0154
15	2	2.5	30	47.313	47.305	0.018177	26.775	26.776	-0.00486
16	2	5	10	41.217	41.203	0.032511	26.380	26.377	0.013267
17	2	5	20	41.050	41.059	-0.02168	25.334	25.340	-0.02566
18	2	5	30	44.999	44.990	0.021111	25.377	25.380	-0.01025
19	2	7.5	10	41.790	41.793	-0.00885	26.301	26.305	-0.01369
20	2	7.5	20	39.705	39.716	-0.0267	24.067	24.075	-0.03282
21	2	7.5	30	44.711	44.701	0.022366	24.925	24.928	-0.01163
22	2	10	10	46.251	46.255	-0.00757	30.492	30.494	-0.00394
23	2	10	20	42.351	42.359	-0.01983	26.462	26.468	-0.02381
24	2	10	30	45.599	45.588	0.025658	25.617	25.619	-0.00781

% TR\* - % Thickness Reduction

% LVF\*\* - % liquid Volume Fraction

	Input			Output						
					Grain Sizes					
				lar	ge	%	Sm	% Difference		
	Mat /	%				Difference			over	
Sr. No.	Process	$TR^*$	%LVF**	ANN	RNN	over ANN	ANN	RNN	ANN	
1	1	2.5	10	54.1875	54.2067	-0.03543	29.5234	29.484	0.133453	
2	1	2.5	20	52.6612	52.6909	-0.0564	34.1046	34.0894	0.044569	
3	1	2.5	30	59.9039	59.9517	-0.07979	37.5049	37.7475	-0.64685	
4	1	5	10	51.05	51.0677	-0.03467	29.0427	29.0233	0.066798	
5	1	5	20	46.2683	45.6567	1.321855	30.6739	30.6757	-0.00587	
6	1	5	30	52.2429	52.2859	-0.08231	33.6145	31.3427	6.758393	
7	1	7.5	10	49.4019	49.4101	-0.0166	29.4733	29.4526	0.070233	
8	1	7.5	20	43.8056	43.8131	-0.01712	29.4299	29.4262	0.012572	
9	1	7.5	30	49.2255	49.2655	-0.08126	28.0999	28.3094	-0.74555	
10	1	10	10	49.0084	49.0092	-0.00163	30.5889	30.5638	0.082056	
11	1	10	20	43.7229	43.7293	-0.01464	29.9121	29.9042	0.026411	
12	1	10	30	49.1137	49.4527	-0.69024	27.3891	27.5708	-0.6634	
13	2	2.5	10	44.8487	44.8163	0.072243	24.5998	24.5705	0.119107	
14	2	2.5	20	42.8446	42.8538	-0.02147	26.5484	26.5529	-0.01695	
15	2	2.5	30	48.2753	48.3038	-0.05904	26.7442	26.9351	-0.7138	
16	2	5	10	43.5371	43.5299	0.016538	24.9919	24.9872	0.018806	
17	2	5	20	39.5439	39.5377	0.015679	25.133	25.1385	-0.02188	
18	2	5	30	43.6984	43.7249	-0.06064	24.7239	24.8992	-0.70903	
19	2	7.5	10	43.6721	43.6584	0.03137	26.2624	26.2512	0.042647	
20	2	7.5	20	38.8598	38.8544	0.013896	25.3776	25.3831	-0.02167	
21	2	7.5	30	42.8648	42.8592	0.013064	25.0421	25.0383	0.015174	
22	2	10	10	44.9272	44.9116	0.034723	28.1909	28.1709	0.070945	
23	2	10	20	40.3236	40.3147	0.022071	26.947	26.9414	0.020782	
24	2	10	30	44.3036	44.3185	-0.03363	26.6612	26.7723	-0.41671	
%	% TR <sup>*</sup> - % Thickness Reduction % LVF <sup>**</sup> - % liquid Volume Fraction									

#### Table: 4 Comparison of grain size predicted by ANN & hybrid RNN after MSE = 0.0001762

% TR<sup>\*</sup> - % Thickness Reduction

ANN with 5-9-6-1 architecture with same values of  $\eta$ = 0.85 and  $\alpha$  = 0.65. We see that the error in estimation lies within |4%|, while the computation time using Hybrid RNN is saved by around 80%.

#### 4.3 Statistical Testing:

In the statistical analysis carried out, three types of tests were conducted which are listed as under:

1. To test equality of two means by using the two sample student\_t test.

			Input	Output		%		
Sr. No.	Materia 1/	% TR*	%LVF**	Grain Sizes		Harc	lness	DIFFERENCE OVER ANN
				large	Small	ANN	RNN	VALUE
1	1	0	0	50	50	78.0613	77.9555	0.135535
2	1	2.5	10	62	27	90.1529	89.3799	0.857432
3	1	2.5	20	58	33	103.241	104.161	-0.89112
4	1	2.5	30	66	37	86.037	86.7449	-0.82279
5	1	5	10	54	25	101.248	100.237	0.998538
6	1	5	20	51	31	111.916	111.436	0.428893
7	1	5	30	55	32	99.031	96.5667	2.488413
8	1	7.5	10	62	32	107.057	107.183	-0.11769
9	1	7.5	20	48	26	116.601	116.431	0.145796
10	1	7.5	30	53	27	102.854	102.386	0.455014
11	1	10	10	49	29	115.604	114.982	0.538044
12	1	10	20	47	30	121.807	120.859	0.77828
13	1	10	30	54	26	107.18	107.595	-0.3872
14	2	0	0	52	28	84.6917	84.7368	-0.05325
15	2	2.5	10	43	27	96.4489	95.235	1.258594
16	2	2.5	20	42	26	105.44	105.405	0.033194
17	2	2.5	30	47	25	90.347	89.418	1.028258
18	2	5	10	42	26	104.18	104.019	0.15454
19	2	5	20	41	25	112.271	112.693	-0.37588
20	2	5	30	46	24	98.266	98.6478	-0.38854
21	2	7.5	10	40	26	111.18	112.016	-0.75193
22	2	7.5	20	39	25	118.164	118.393	-0.1938
23	2	7.5	30	45	24	106.062	106.752	-0.65056
24	2	10	10	47	32	115.232	115.346	-0.09893
25	2	10	20	43	25	121.191	121.019	0.141925
26	2	10	30	45	27	113.495	112.567	0.817657

# Table5. Comparison of ANN & hybrid RNN for hardness prediction using 5-5-3-1 architecture

% TR\* - % Thickness Reduction

% LVF\*\* - % liquid Volume Fraction

			Input	Output		% DIEEEDENCE		
Sr. No.	Mat / Process	% TR <sup>*</sup>	%LVF**	Grain	Sizes	Hardness		% DIFFERENCE OVER ANN
				large	Small	ANN	RNN	VALUE
1	1	0	0	50	50	67.9705	69.231	-1.85448
2	1	2.5	10	62	27	89.7614	93.22	-3.8531
3	1	2.5	20	58	33	103.16	101.879	1.24176
4	1	2.5	30	66	37	86.0228	87.2178	-1.38917
5	1	5	10	54	25	99.6521	101.178	-1.53123
6	1	5	20	51	31	111.04	112.874	-1.65166
7	1	5	30	55	32	96.483	96.8224	-0.35177
8	1	7.5	10	62	32	107.059	106.62	0.410054
9	1	7.5	20	48	26	115.966	116.751	-0.67692
10	1	7.5	30	53	27	102.586	102.287	0.291463
11	1	10	10	49	29	115.246	117.323	-1.80223
12	1	10	20	47	30	120.33	119.63	0.581734
13	1	10	30	54	26	107.765	108.413	-0.60131
14	2	0	0	52	28	57.2824	58.824	-2.69123
15	2	2.5	10	43	27	95.179	98.8946	-3.9038
16	2	2.5	20	42	26	106.801	105.267	1.436316
17	2	2.5	30	47	25	90.3766	91.543	-1.2906
18	2	5	10	42	26	103.904	104.088	-0.17709
19	2	5	20	41	25	113.233	112.989	0.215485
20	2	5	30	46	24	98.7331	97.684	1.062562
21	2	7.5	10	40	26	111.772	110.56	1.08435
22	2	7.5	20	39	25	118.619	117.936	0.575793
23	2	7.5	30	45	24	106.473	105.934	0.506232
24	2	10	10	47	32	115.947	115.17	0.670134
25	2	10	20	43	25	120.866	119.493	1.135969
26	2	10	30	45	27	112.755	114.811	-1.82342

#### Table6. Comparison of ANN & hybrid RNN for hardness prediction using 5-9-6-1 architecture

% TR<sup>\*</sup> - % Thickness Reduction

- 2. To test if the given population has standard normal distribution using one sample Kolmogorov – Smirnov test.
- Testing if the two populations belong to the same continuous distribution using two samples Kolmogorov – Smirnov test.

% LVF\*\*\* - % liquid Volume Fraction

K-s test for single sample and two samples were used to test the normality of the distribution of errors in prediction of grain sizes (Large and Small grain sizes) and hardness as predicted by ANN and HRNN with different architectures mentioned at 3.1 and 3.2 above. The errors were calculated between the predicted values obtained from ANN and actual values and also between the predicted values obtained from HRNN and actual values. A third type of error was calculated between the values predicted by HRNN and ANN. Further to this, two sample student\_t – test was performed for testing the equality of means of populations representing the errors between ANN and HRNN predictions for large grain size, small grain size and hardness. To be able to analyze the data more meaningfully, the population of errors was divided into errors in predictions for as cast Al-4.5Cu-5TiB<sub>2</sub> composite and pre hot rolled Al-4.5Cu-5TiB<sub>2</sub> composite. For the purpose of statistical analysis of the performance of HRNN with the parent ANN, the following terminology of errors is defined.

- a. Error (a): Error in prediction of large grain size and small grain size by ANN with 4-7-4-2 architecture over the target values.
- b. Error (b); Error in prediction of large grain size and small grain size by HRNN with 4-7-4-2 architecture over the target values.
- c. Error(c); Error in prediction of large grain size and small grain size by ANN with 4-9-9-2 architecture over the target values.
- d. Error (d); Error in prediction of large grain size and small grain size by HRNN with 4-9-9-2 architecture over the target values.
- e. Error (e); Error in prediction of hardness by ANN with 5-5-3-1 architecture over the target values.
- f. Error (e); Error in prediction of hardness by HRNN with 5-5-3-1 architecture over the target values.
- g. Error (e); Error in prediction of hardness by ANN with 5-9-6-1 architecture over the target values.
- h. Error (e); Error in prediction of hardness by HRNN with 5-9-6-1 architecture over the target values.

#### 4.3.1 Testing of equality of means:

Table: 7 gives the results of the two sample student\_t test performed on the population deduced from the predictions of HRNN and ANN with different architectures. It can be seen that the means of the HRNN prediction populations are comparable to the mean values of populations obtained from ANN predictions for similar architectures. Furthermore, the standard deviation values also are comparable for similar architectures of ANN and HRNN.

In testing of hypothesis, the strength of the conclusion is decided by level of significance  $\alpha$ . The popular value of  $\alpha$  is 0.05. The decision about the test is based on the value of the test statistics obtained from the sample and the benchmark value of appropriate test statistics obtained from the tables, using  $\alpha$  and degrees of freedom (which can always be obtained from the size of sample).

However, while reporting the conclusion, the value of test statistic obtained is never reported. As a result, closeness of this test value obtained from the sample and the bench mark value of appropriate test statistic also does not get reported.

This difficulty is overcome when p value of test is indicated. The p value indicates the probability of obtaining a test statistic as extreme as the one actually observed, assuming that the null hypothesis is true.

# 4.3.2 Testing errors for standard normal distribution :

Testing of the error distribution of ANN and HRNN predictions over target values of large grain sizes, small grain sizes and hardness was carried out using one sample Kolmogorov – Smirnov test. For this purpose, the various errors as defined in section 4.3 were considered. The results of the test are tabulated in Table 8. It can be seen that with a confidence of 5% ( $\alpha = 0.05$ ), used for the test, all the error distributions i.e. Error (a) to Error (h) are accepted as standard normal distributions. Table 8 gives the p values for all the error distributions. H<sub>0</sub> indicates that the error population has normal distribution, while H<sub>1</sub> indicates that the error population.

#### 4.3.3 Testing for equality of continuous distributions using Two Sample Kolmogorov – Smirnov test.

Here the distribution of errors between ANN predicted values for grain sizes using 4-7-4-2 and 4-9-9-2 architectures over target values of grain sizes were checked with their counterparts predicted by HRNN with similar architectures, for equality. The same test was carried out to check the equality of similar error distributions obtained using HRNN and ANN for hardness using 5-5-3-1 and 5-9-6-1

architectures. The results of this test are presented in Table 9.  $H_0$  indicates that the two error distributions

under test are equal, while  $H_1$  indicates that they are not equal.

		Large grain size / h	ardness (HRNN)	Small grain size/hardness (ANN)		
Architec	ture	Populat	ion 1	Population 2		
		As cast	Pre hot rolled	As cast	Pre hot rolled	
4742	Mean:	-0.0334	0.0034	-0.0136	0.0047	
4-7-4-2	Stdv:	0.0401	0.0068	0.0244	0.0026	
4002	Mean:	-0.0201	-0.0134	-0.0053	0.0052	
4-9-9-2	Stdv:	0.0099	0.0073	0.0022	0.0015	
5521	Mean:	0.8248			1.2176	
5-5-5-1	Stdv:	2.8327			2.0481	
5061	Mean:	-1.9638			-2.6684	
5-9-0-1	Stdv:	2.3999			2.1505	

#### TABLE7. Results of two sample student\_t test

#### TABLE8. Results of one sample Kolmogorov – Smirnov test.

Test No.	α	Errors	p va	Conclusion	
			Large grain size / hardness	Small grain size	
А	0.05	Error(a)	0.7366	0.8174	H <sub>0</sub> : Accepted
В	0.05	Error(b)	0.8174	0.0940	H <sub>0</sub> : Accepted
С	0.05	Error(c)	0.1879	0.1860	H <sub>0</sub> : Accepted
D	0.05	Error(d)	0.1983	0.1901	H <sub>0</sub> : Accepted
E	0.05	Error(e)	0.5502		H <sub>0</sub> : Accepted
F	0.05	Error(f)	0.2993		H <sub>0</sub> : Accepted
G	0.05	Error(g)	0.3258		H <sub>0</sub> : Accepted
Н	0.05	Error(h)	0.1499		H <sub>0</sub> : Accepted

#### TABLE9. Results of two sample Kolmogorov – Smirnov test.

			p va		
Test No.	Population of errors tested	α	Large grain size / hardness	Small grain size	Conclusion
А	Error(a) v/s Error(b)	0.05	0.9999	0.1094	H <sub>0</sub> : Accepted
В	Error(a) v/s Error(b)	0.05	0.9999	0.9999	H <sub>0</sub> : Accepted
С	Error(a) v/s Error(b)	0.05	0.2581		H <sub>0</sub> : Accepted
D	Error(a) v/s Error(b)	0.05	0.8922		H <sub>0</sub> : Accepted

#### 5. Conclusions:

1. It is seen that the Simple Elman Recurrent Network does not necessarily converge for all the applications, as is seen in the present case. The SRN modeled for the predictions of grain sizes and hardness failed to converge despite all possible architectures being tried with various combinations of learning rate parameter ( $\eta$ ) and momentum factor ( $\alpha$ ).

2. The slight modification in the network architecture with the neurons in the hidden layers giving feed back to itself resulted in

slightly better convergence, but the learning was not good enough to do correct mappings.

- 3. A Hybrid Recurrent Network constructed by borrowing weights form a partially trained FFNN with similar architecture is found to excellently converge and is able to predict the outputs comparable with those predicted by the parent FFNN / ANN. The Network training time is drastically reduced by employing such Hybrid Recurrent Neural Networks as have been demonstrated by the four cases considered.
- 4. The test on normality of the errors justifies the stability of the model. Secondly, the test on the two means confirms that the HRNN and the parent FFNN are not significantly different in behavior. Likewise, the distribution of errors obtained with parent FFNN and HRNN also confirm that they have equivalent performance capabilities. This equivalent performance coupled with the reduced learning time provides a strong potential for use of HRNN in real time process control applications.

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