

Fig. 1.2. b Result of simulation for speed of turbine without UPQC

In this result the sag problem is created in this paper and the torque is not smooth . There is phase jump problems is also found

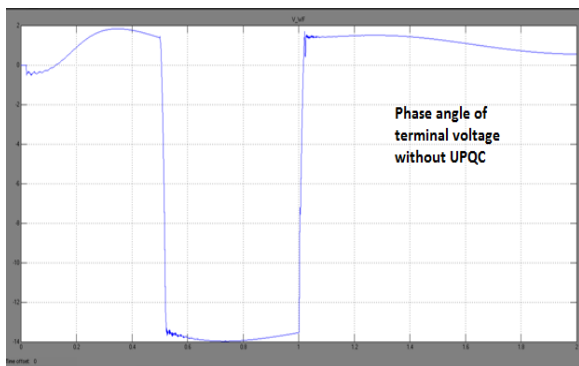
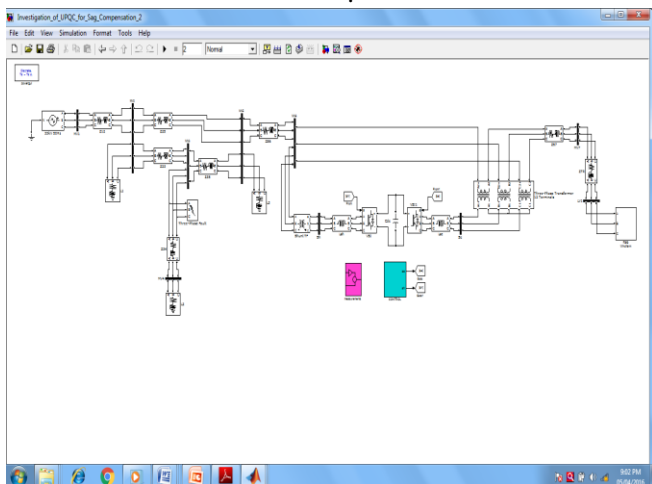


Fig shows the phase angle jump without UPQC

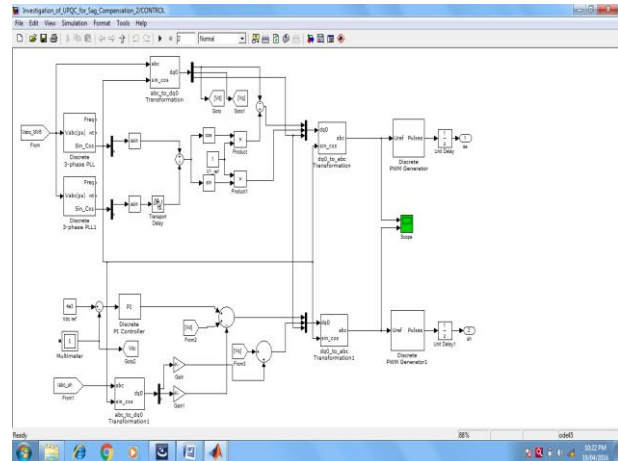
### III. USING UPQC



COMPENSATION OF VOLTAGE FLUCTUATION  
Simulation results for  $0 < t < 6$  are shown. At  $t = 0.5$  "Begins the cyclical power pulsation produced by the tower shadow

effect. As was mentioned, the tower shadow produces variation in torque, and hence in the active and reactive WF generated power. For nominal wind speed condition, the power fluctuation frequency is  $f = 3.4\text{Hz}$ , and the amplitude of the resulting voltage variation at PCC, expressed as a percentage is:  $dU/ U_{rated} = 1.50\%$  .

### IV. UPQC CONTROL STRATEGIE



Control strategy plays the most significant role in any powerelectronics based system. It is the control strategy which decides the behavior and desired operation of a particular system. The effectiveness of a UPQC system solely depends upon its control algorithm. The UPQC control strategy determines the reference signals (current and voltage) and, thus, decides the switching instants of inverter switches, such that the desired performance can be achieved. There are several control strategies/algorithm/techniques available in the existing literature those have successfully applied to UPQC systems. Frequency domain methods, such as, based on the fast Fourier transformer (FFT), are not popular due to large computation time and delay in calculating the FFT. Control methods for UPQC in the time domain are based on instantaneous derivation of compensating commands in the form of either voltage or current signals.

There are a large number of control methods in the time domain. Two most widely used time-domain control techniques for UPQC are the instantaneous active and reactive power or three phase *pq* theory [10] and synchronous reference frame method or three-phase *dq* theory [10].

These methods transfer the voltage and current signals in ABC frame to stationary reference frame (*pq* theory) or synchronously rotating frame (*dq* theory) to separate the fundamental and harmonic quantities. In *pq* theory, instantaneous active and reactive powers are computed, while, the *d-q* theory deals with the current independent of the supply voltage. The interesting feature of these theories is that the real and reactive powers associated with fundamental components (*pq* theory), and the fundamental component in distorted voltage or current (*dq* theory), are dc quantities.

These quantities can easily be extracted using an LPF or a high-pass filter (HPF). Due to the dc signal extraction,

filtering of signals in the  $\alpha\beta$  reference frame is insensitive to any phase shift errors introduced by LPF.

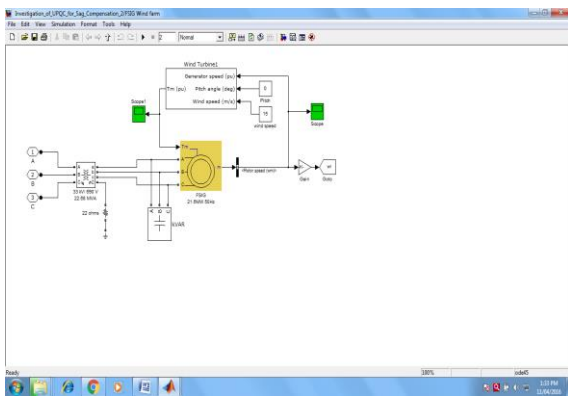
However, the cutoff frequency of these LPF or HPF can affect the dynamic performance of the controller. The UPQC serial converter is controlled to maintain the WF terminal voltage at nominal value, thus compensating the PCC voltage variations. In this way, the voltage disturbances coming from the grid cannot spread to the WF facilities.

As a side effect, this control action may increase the low voltage ride-through (LVRT) capability in the occurrence of voltage sags in the WF terminals. Fig. 2. Shows a block diagram of the series converter controller. The injected voltage is obtained subtracting the PCC voltage from the reference voltage, and is phase-aligned with the PCC voltage. On the other hand, the shunt converter of UPQC is used to filter the active and reactive power pulsations generated by the WF. Thus, the power injected into the grid from the WF compensator set will be free from pulsations, which are the origin of voltage fluctuation that can propagate into the system. This task is achieved by appropriate electrical currents injection in PCC. Also, the regulation of the DC bus voltage has been assigned to this converter. This controller generates both voltages commands.

The powers  $P_{shuC}$  and  $Q_{shuC}$  are calculated in the rotating reference frame, as follows:

$$P_{shuC}(t) = 3/2 \cdot V^{PCC}_d(t) \cdot I^{shuC}_d(t)$$

$$Q_{shuC}(t) = -3/2 \cdot V^{PCC}_d(t) \cdot I^{shuC}_q(t)$$



Model of induction generator

For the squirrel cage induction generator the model available in MATLAB/ Simulink Sim Power Systems libraries is used. It consists of a fourth order state space electrical model and a second order mechanical model

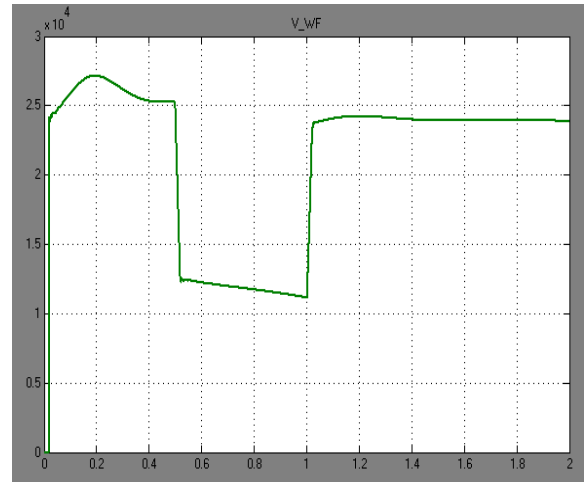
$$= 2/3 \begin{bmatrix} \sin \theta & \sin \left( \theta - \frac{2\pi}{3} \right) & \sin \left( \theta + \frac{2\pi}{3} \right) \\ \cos \theta & \cos \left( \theta - \frac{2\pi}{3} \right) & \cos \left( \theta + \frac{2\pi}{3} \right) \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} f_d \\ f_q \\ f_o \end{bmatrix} = T \cdot \begin{bmatrix} f_a \\ f_b \\ f_c \end{bmatrix}$$

Where  $f_i=a,b,c$  represents either phase voltage or currents, and  $f_i=d,q,0$  represents that magnitudes transformed to the

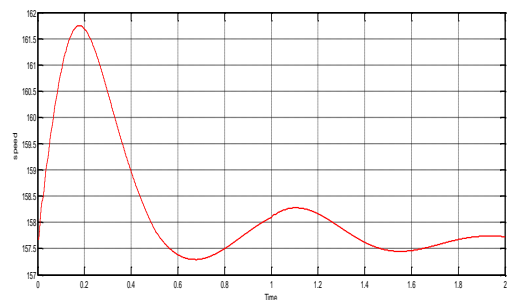
dqo space. This transformation allows the alignment of a rotating reference frame with the positive sequence of the PCC voltages space vector. To accomplish this, a reference angle  $\theta$  synchronized with the PCC positive sequence fundamental voltage space vector is calculated using a Phase Locked Loop (PLL) system. In this work, an “instantaneous power theory” based PLL has been implemented. Under balance steady-state conditions, voltage and currents vectors in this synchronous reference frame are constant quantities

A. Simulation result of terminal voltage

The voltage sag problem is compensated by using UPQC device



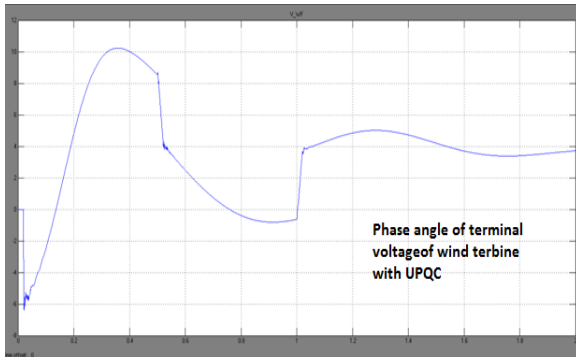
B. Simulation result of speed means smooth torque



As we seen that the torque of wind turbine is smooth with UPQC. The custom power devices compensate the power quality problems .

1) Maintain Stability of the system and regulate voltage, Improve power factor and also mitigate power quality problems. This feature is useful for analysis and decoupled control.  $E_d$   $shuC$  and  $E_q$   $shuC$  based on power fluctuations  $P$  and  $Q$ , respectively. Such deviations are calculated subtracting the mean power from the instantaneous power measured in PCC  $E_d$   $shuC$  also contains the control action for the DC-bus voltage loop.

### C. Simulation result of phase jump



## V. VOLTAGE REGULATION

As stated in Sec. I, the UPQC is also operated to maintain the WF terminal voltage constant, rejecting PCC voltage variations, due to events like sudden connection/disconnection of loads, power system faults, etc. A sudden connection of load is performed at  $t = 6$  s, by closing L3 switch (SW). As can be observed in the upper curve, the series converter requires negligible power to operate, while the shunt converter demands a high instantaneous power level from the capacitor when compensating active power fluctuation. Compensation of reactive powers has no influence on the DC side power. The DC-bus has voltage level limitations in accordance with the VSI's operational characteristics. As the fluctuating active power is handled by the capacitor, its value needs to be selected so that the "ripple" in the DC voltage is kept within a narrow range. In this case, I have considered a capacitor size  $C = 0.42$  F. This high value can be easily obtained by using emerging technologies based capacitors, such as double-layer capacitors, also known as ultra capacitors.

## VI CONCLUSION

The model of the power system scheme illustrated in Fig.1, including the controllers with the control strategy detailed in II, was implemented using MATLAB/ Simulink software. Numerical simulations were performed to determine and then compensate voltage fluctuation due to wind power variation, and voltage regulation problems due to a sudden load connection. The simulation was conducted with the following chronology. In this paper, a new compensation strategy implemented using an UPQC type compensator was presented, to connect SCIG based wind farms to weak distribution power grid. The proposed compensation scheme enhances the system power quality, exploiting fully DC-bus energy storage and active power sharing between UPQC converters, features not present in DVR and D-Statcom compensators. The simulation results show a good performance in the rejection of power fluctuation due to "tower shadow effect" and the regulation of So, the effectiveness of the proposed compensation approach is demonstrated in the study case. There are two important types of APF, namely, shunt APF and series APF [8]–[10]. The shunt APF is the most promising to tackle the current-related problems, whereas, the series APF is the most suitable to overcome the voltage-related problems Since the modern

distribution system demands a better quality of voltage being supplied and current drawn, installation of these APFs has great scope in actual practical implementation.

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